**Tasks To-Do**

* ~~Meet with Ryan McGovern regarding robotic arm~~
* ~~Install all software on laptop~~
* ~~Setup Anaconda on laptop~~
* ~~Try to understand existing code for robotic arm~~
* ~~Understand how to move robotic arm in different ways~~
* ~~3D print holder for GoPro on robotic arm~~
* ~~Attach GoPro holder to end effector of robotic arm~~
* ~~Figure out how to connect camera to robotic arm~~
* ~~Acquire raspberry pi zero for remote control~~
* ~~Remotely control GoPro (possibly connect to raspberry pi or Arduino)~~
* Read book about photogrammetry (Photogrammetric Computer Vision by Wolfgang Forstner)
* ~~Download / Install photogrammetry software~~
* Attempt photogrammetry with GoPro
* Review results of photogrammetry with GoPro
* Attempt other photogrammetry capture methods (other than GoPro)
* ~~Implement remote control GoPro code into main system~~
* ~~Implement GoPro remote control into web interface~~
* Implement Livestreaming of GoPro into web interface
* Create / Find Turntable
* Create / Find Lighting Systems
* ~~Implement PiCamera into web interface~~
* ~~Implement livestreaming into GoPro and PiCamera interfaces~~

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